## Gear Down for Speed Worksheet

1. Measure the diameter and calculate the circumference of the wheels of your robot. The formula for the circumference of a circle is:

Circumference $=$ pi $\times$ diameter
Wheel Type
Wheel Diameter
Circumference
2. Using a $1 / 1$ gear ratio, measure the distance traveled by the robot and compute its speed. Using the following formula, calculate the speed for different gear ratios:

Gear Ratio $1 \times$ Speed 1= Gear Ratio2 x Speed 2

| Gear Ratio 1 | $1 / 1$ |
| :---: | :---: |
| Speed 1 | Speed 2 |
| Gear Ratio 2 |  |
| $8 / 24$ |  |
| $8 / 40$ |  |
| $2 / 40$ |  |

3. Calculate the speed of the robot by attaching gears in different configurations:

| Gear Ratio | Distance Traveled | Time | Speed |
| :---: | :---: | :---: | :---: |
| $8 / 24$ |  |  |  |
| $8 / 40$ |  |  |  |
| $24 / 40$ |  |  |  |

4. Compare the values for Speed in step 3 with Speed2 in step 2.
5. Now using your own configuration of gears, and wheels how fast can you make your robot?!!
